

W3G800-GV01-01/F02

# EC axial fan - HyBlade

sickle-shaped blades (S series)

with square full nozzle



## Nominal data

<b>Type</b>	W3G800-GV01-01/F02	
<b>Motor</b>	M3G150-NA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min <sup>-1</sup>	1090
Power consumption	W	2980
Current draw	A	4.5
Max. back pressure	Pa	260
Max. back pressure	in. wg	1.04
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	65

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment  
Subject to change

## Data according to Commission Regulation (EU) 327/2011

		Actual	Req. 2015
01 Overall efficiency $\eta_{es}$	%	43.2	36.3
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		46.9	40
05 Variable speed drive		Yes	

Data obtained at optimum efficiency level.  
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

09 Power consumption $P_{ed}$	kW	2.6
09 Air flow $q_v$	m <sup>3</sup> /h	18115
09 Pressure increase $p_{fs}$	Pa	212
10 Speed (rpm) n	min <sup>-1</sup>	1080
11 Specific ratio*		1.00

\* Specific ratio =  $1 + p_{fs} / 100\,000\text{ Pa}$

LU-113933



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## Technical description

<b>Weight</b>	52 kg
<b>Size</b>	800 mm
<b>Motor size</b>	150
<b>Rotor surface</b>	Painted black
<b>Electronics housing material</b>	Die-cast aluminum, painted black
<b>Blade material</b>	Sheet aluminum insert, sprayed with PP plastic
<b>Fan housing material</b>	Sheet steel, pre-galvanized and coated with black plastic (RAL 9005)
<b>Guard grille material</b>	Steel, coated with black plastic (RAL 9005)
<b>Number of blades</b>	5
<b>Blade pitch</b>	0°
<b>Airflow direction</b>	V
<b>Direction of rotation</b>	Clockwise, viewed toward rotor
<b>Degree of protection</b>	IP55
<b>Insulation class</b>	"F"
<b>Moisture (F) / Environmental (H) protection class</b>	F4-1
<b>Max. permitted ambient temp. for motor (transport/storage)</b>	+ 80 °C
<b>Min. permitted ambient temp. for motor (transport/storage)</b>	- 40 °C
<b>Installation position</b>	Shaft horizontal or rotor on bottom; rotor on top on request
<b>Condensation drainage holes</b>	On rotor side
<b>Mode</b>	S1
<b>Motor mounting</b>	Ball bearing
<b>Technical features</b>	<ul style="list-style-type: none"> <li>- Output 10 VDC, max. 10 mA</li> <li>- Output 20 VDC, max. 50 mA</li> <li>- Output for slave 0-10 V</li> <li>- Operation and alarm display</li> <li>- Input for sensor 0-10 V or 4-20 mA</li> <li>- External 24 V input (parameter setting)</li> <li>- External release input</li> <li>- Alarm relay</li> <li>- Integrated PID controller</li> <li>- Motor current limitation</li> <li>- PFC, passive</li> <li>- RS-485 MODBUS-RTU</li> <li>- Soft start</li> <li>- Control input 0-10 VDC / PWM</li> <li>- Control interface with SELV potential safely disconnected from supply</li> <li>- Thermal overload protection for electronics/motor</li> <li>- Line undervoltage / phase failure detection</li> </ul>
<b>EMC immunity to interference</b>	According to EN 61000-6-2 (industrial environment)
<b>EMC interference emission</b>	According to EN 61000-6-3 (household environment)
<b>Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)</b>	<= 3.5 mA
<b>Electrical hookup</b>	Terminal box
<b>Motor protection</b>	Reverse polarity and locked-rotor protection
<b>Protection class</b>	I (with customer connection of protective earth)
<b>Approval</b>	UL 1004-7 + 60730;

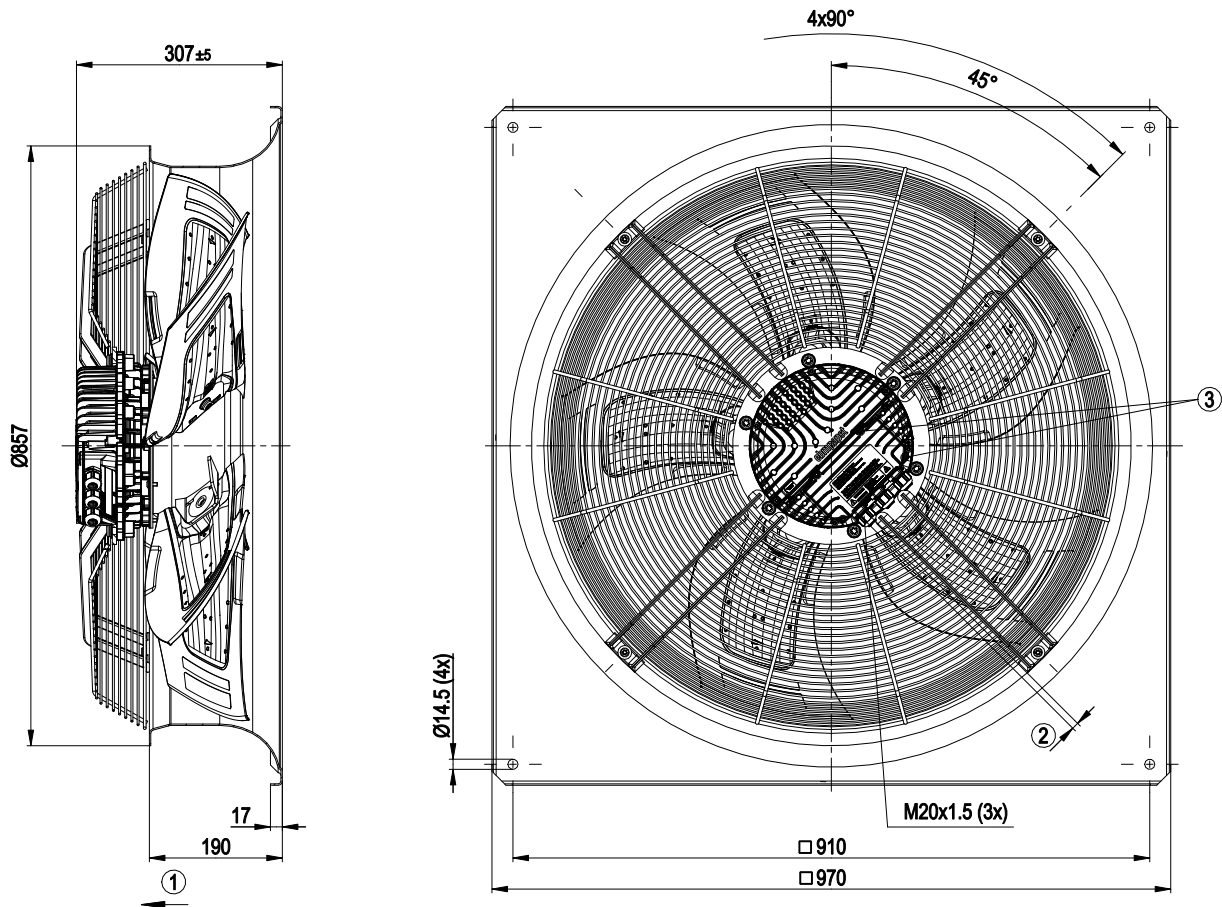


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## Product drawing



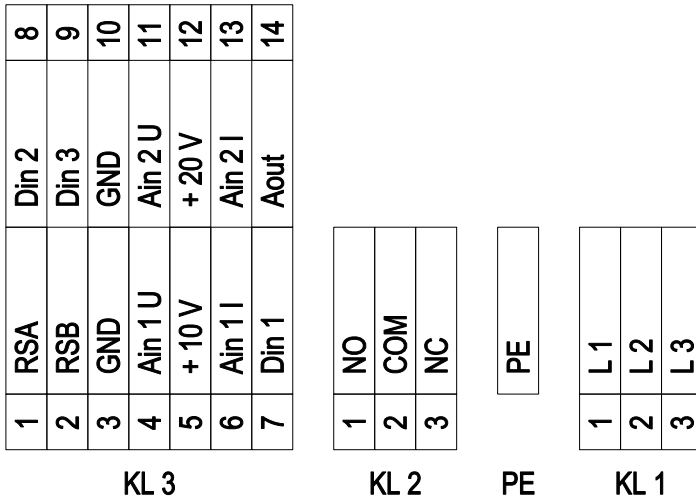
1	Direction of air flow "V"
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque $4 \pm 0.6$ Nm
3	Tightening torque $3.5 \pm 0.5$ Nm

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## Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact; make for failure
KL2	2	COM	Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ±5/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV



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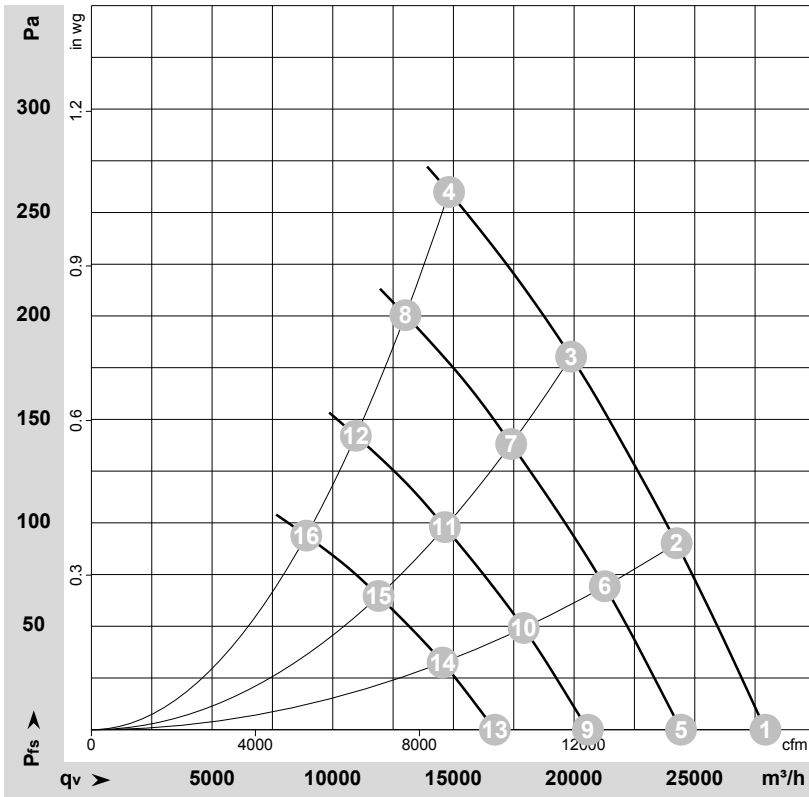
No.	Conn.	Designation	Function/assignment
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, $R_i = 100 \Omega$ , adjustable curve, only usable as alternative to input Ain2U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV

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## Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2 \%$

Measurement: LU-113933-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

## Measured values

	U	f	n	P <sub>ed</sub>	I	LpA <sub>in</sub>	LwA <sub>in</sub>	LwA <sub>out</sub>	q <sub>v</sub>	P <sub>fs</sub>	q <sub>v</sub>	P <sub>fs</sub>
	V	Hz	min <sup>-1</sup>	W	A	dB(A)	dB(A)	dB(A)	m <sup>3</sup> /h	Pa	cfm	in. wg
1	400	50	1090	1867	2.83	69	76	77	27930	0	16440	0.00
2	400	50	1090	2208	3.35	69	76	76	24245	90	14270	0.36
3	400	50	1090	2534	3.87	72	79	78	19875	180	11700	0.72
4	400	50	1090	2980	4.50	77	85	84	14820	260	8725	1.04
5	400	50	950	1250	1.90	65	73	74	24430	0	14380	0.00
6	400	50	950	1491	2.26	66	73	73	21270	69	12520	0.28
7	400	50	950	1697	2.59	69	75	74	17395	138	10240	0.55
8	400	50	950	1936	2.95	74	82	81	13010	200	7660	0.80
9	400	50	800	746	1.13	61	68	69	20575	0	12110	0.00
10	400	50	800	890	1.35	62	68	68	17910	49	10540	0.20
11	400	50	800	1013	1.55	64	71	70	14645	98	8620	0.39
12	400	50	800	1156	1.76	70	77	77	10960	142	6450	0.57
13	400	50	650	400	0.61	56	63	64	16715	0	9840	0.00
14	400	50	650	477	0.73	56	63	63	14550	33	8565	0.13
15	400	50	650	543	0.83	59	66	65	11900	65	7005	0.26
16	400	50	650	620	0.95	64	72	71	8905	94	5240	0.38

U = Power supply · f = Frequency · n = Speed (rpm) · P<sub>ed</sub> = Power consumption · I = Current draw · LpA<sub>in</sub> = Sound pressure level intake side · LwA<sub>in</sub> = Sound power level intake side  
 LwA<sub>out</sub> = Sound power level outlet side · q<sub>v</sub> = Air flow · P<sub>fs</sub> = Pressure increase

