

R3G630-RB21-61-S01

Emerson

# EC centrifugal fan - RadiCal

backward-curved, single-intake

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### Nominal data

Type	R3G630-RB21-61-S01	
Motor	M3G150-IF	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min <sup>-1</sup>	1300
Power consumption	W	2700
Current draw	A	4.1
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	55

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment  
Subject to change

### Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency $\eta_{es}$	%	65.7	56.1
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		71.6	62
05 Variable speed drive		Yes	

Data obtained at optimum efficiency level.

The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

09 Power consumption $P_{ed}$	kW	2.76
09 Air flow $q_v$	m <sup>3</sup> /h	11165
09 Pressure increase $p_{fs}$	Pa	553
10 Speed (rpm) n	min <sup>-1</sup>	1305
11 Specific ratio*		1.01

\* Specific ratio =  $1 + p_{fs} / 100\,000\text{ Pa}$

LU-137530



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## Technical description

<b>Weight</b>	31 kg
<b>Fan size</b>	630 mm
<b>Rotor surface</b>	Painted black
<b>Electronics housing material</b>	Die-cast aluminum
<b>Impeller material</b>	PP plastic
<b>Number of blades</b>	6
<b>Direction of rotation</b>	Clockwise, viewed toward rotor
<b>Degree of protection</b>	IP55
<b>Insulation class</b>	"F"
<b>Moisture (F) / Environmental (H) protection class</b>	F4-1
<b>Max. permitted ambient temp. for motor (transport/storage)</b>	+80 °C
<b>Min. permitted ambient temp. for motor (transport/storage)</b>	-40 °C
<b>Installation position</b>	Shaft horizontal or rotor on bottom
<b>Condensation drainage holes</b>	On rotor side
<b>Mode</b>	S1
<b>Motor bearing</b>	Ball bearing
<b>Technical features</b>	<ul style="list-style-type: none"> <li>- Output 10 VDC, max. 10 mA</li> <li>- Output 20 VDC, max. 50 mA</li> <li>- Output for slave 0-10 V</li> <li>- Operation and alarm display</li> <li>- Input for sensor 0-10 V or 4-20 mA</li> <li>- External 24 V input (parameter setting)</li> <li>- External release input</li> <li>- Alarm relay</li> <li>- Integrated PID controller</li> <li>- Motor current limitation</li> <li>- PFC, passive</li> <li>- RS-485 MODBUS-RTU</li> <li>- Soft start</li> <li>- Control input 0-10 VDC / PWM</li> <li>- Control interface with SELV potential safely disconnected from the mains</li> <li>- Thermal overload protection for electronics/motor</li> <li>- Line undervoltage / phase failure detection</li> </ul>
<b>EMC immunity to interference</b>	According to EN 61000-6-2 (industrial environment)
<b>EMC interference emission</b>	According to EN 61000-6-4 (industrial environment)
<b>Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)</b>	<= 3.5 mA
<b>Leakage current (measuring circuit according to IEC 60990, Fig. 4, TN system); normal operation</b>	<= 3.5 mA
<b>Leakage current (measuring circuit according to IEC 60990, Fig. 4, TN system); phase failure</b>	<= 3.5 mA



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<b>Leakage current (measured with TrueRMS ammeter); normal operation</b>	< 6 mA
<b>Leakage current (measured with TrueRMS ammeter); phase failure</b>	< 6 mA
<b>Electrical hookup</b>	Via terminal box
<b>Motor protection</b>	Reverse polarity and locked-rotor protection
<b>Protection class</b>	I (with customer connection of protective earth)
<b>Conformity with standards</b>	EN 61800-5-1; CE
<b>Approval</b>	UL 1004-7 + 60730; C22.2 No.77 + CAN/CSA-E60730-1



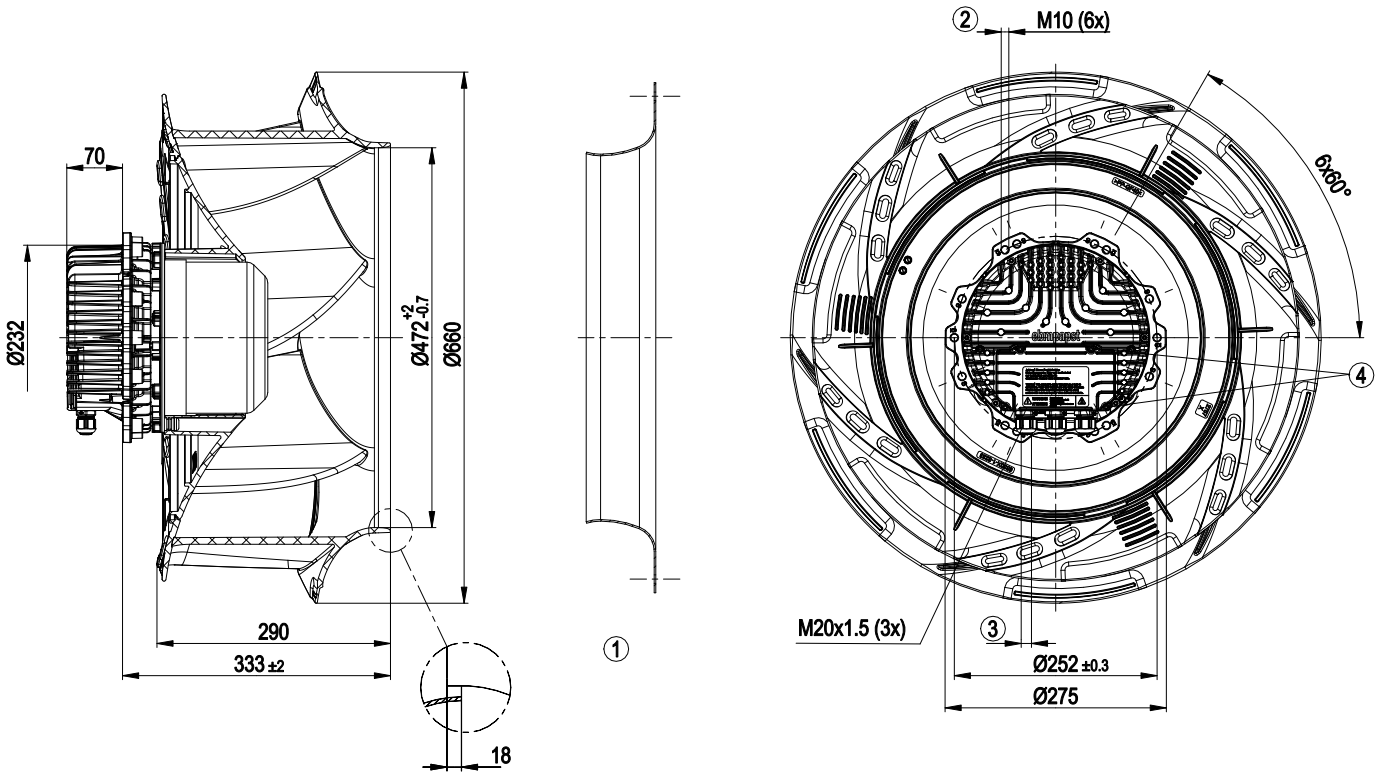
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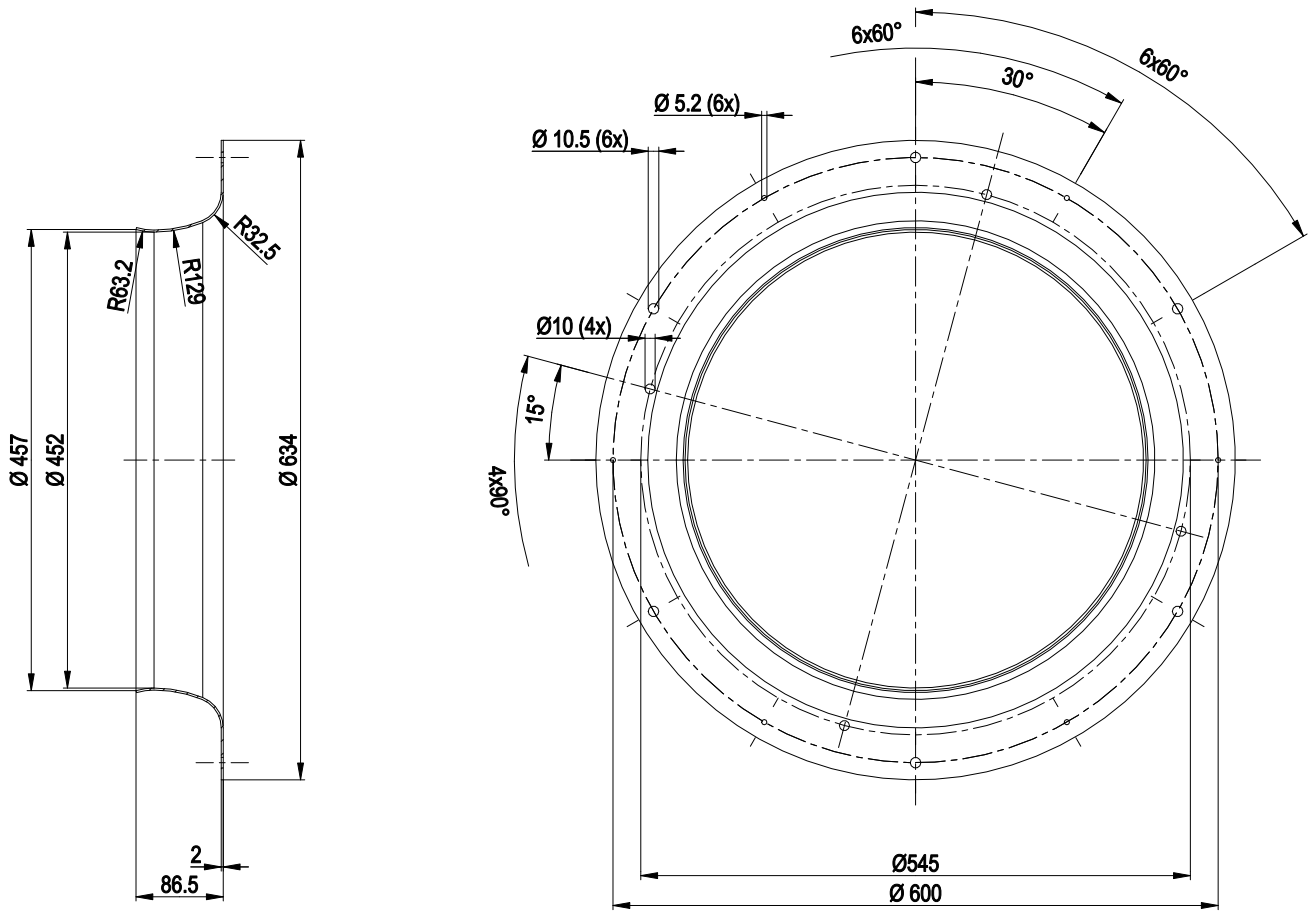
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## Product drawing



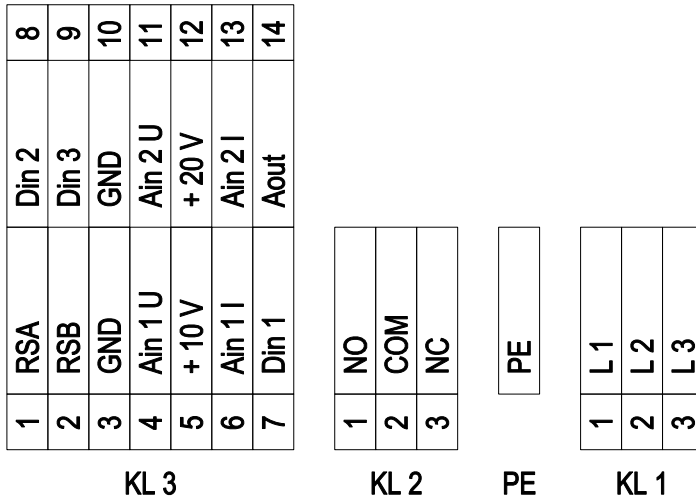
1	Accessory part: inlet ring 63300-2-4013 not included in scope of delivery
2	Max. clearance for screw 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque $4 \pm 0.6$ Nm
4	Tightening torque $3.5 \pm 0.5$ Nm

## Accessory part



Accessory part: inlet ring 63300-2-4013 not included in scope of delivery

## Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact; make for failure
KL2	2	COM	Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V ±5/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV

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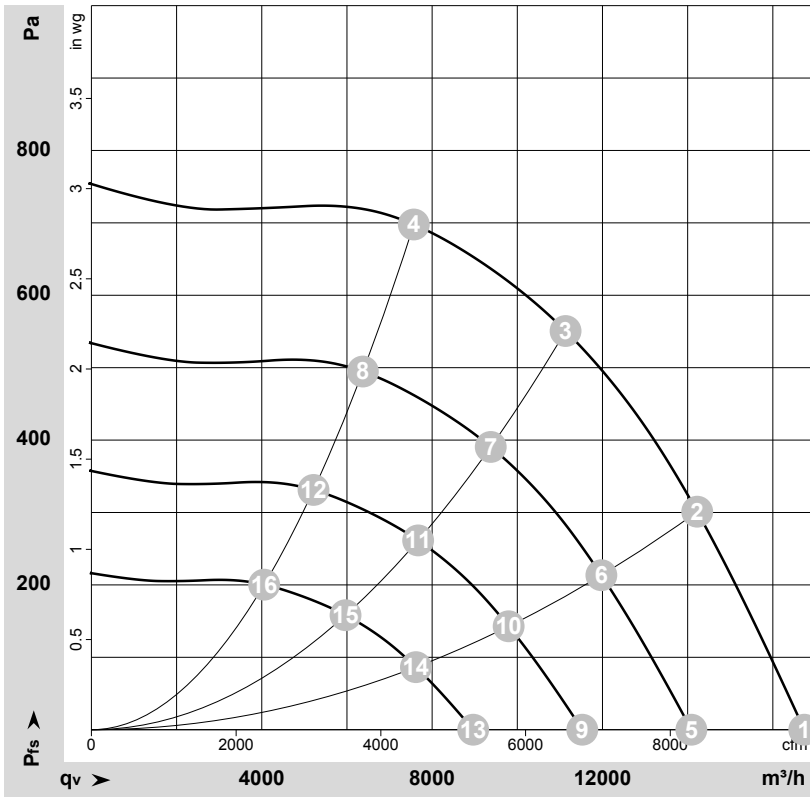
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No.	Conn.	Designation	Function/assignment
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV



## Curves: Air performance 50 Hz



$\rho = 1.15 \text{ kg/m}^3 \pm 2\%$

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebmpapst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

## Measured values

	Wired	U	f	n	P <sub>ed</sub>	I	LpA <sub>in</sub>	LwA <sub>in</sub>	LwA <sub>out</sub>	qv	p <sub>fs</sub>	qv	p <sub>fs</sub>
		V	Hz	min <sup>-1</sup>	W	A	dB(A)	dB(A)	dB(A)	m <sup>3</sup> /h	Pa	CFM	inH <sub>2</sub> O
1	Y	400	50	1300	1779	2.93	79	86	91	16740	0	9850	0.00
2	Y	400	50	1300	2451	3.96	73	80	85	14225	300	8370	1.20
3	Y	400	50	1300	2700	4.10	70	76	81	11135	550	6555	2.21
4	Y	400	50	1300	2640	4.00	73	80	84	7570	700	4455	2.81
5	Y	400	50	1100	1060	1.75	75	82	86	14085	0	8290	0.00
6	Y	400	50	1100	1461	2.36	69	76	81	11975	215	7050	0.86
7	Y	400	50	1100	1649	2.65	65	72	77	9375	393	5520	1.58
8	Y	400	50	1100	1577	2.53	68	76	80	6375	497	3750	2.00
9	Y	400	50	900	581	0.96	70	77	81	11525	0	6785	0.00
10	Y	400	50	900	800	1.29	64	71	76	9795	144	5765	0.58
11	Y	400	50	900	903	1.45	60	67	72	7670	263	4515	1.06
12	Y	400	50	900	864	1.39	63	71	75	5215	333	3070	1.34
13	Y	400	50	700	273	0.45	63	70	75	8965	0	5275	0.00
14	Y	400	50	700	376	0.61	58	64	70	7620	87	4485	0.35
15	Y	400	50	700	425	0.68	54	61	66	5965	159	3510	0.64
16	Y	400	50	700	406	0.65	57	64	68	4055	201	2385	0.81

Wired = Wiring · U = Power supply · f = Frequency · n = Speed (rpm) · P<sub>ed</sub> = Power consumption · I = Current draw · LpA<sub>in</sub> = Sound pressure level intake side · LwA<sub>in</sub> = Sound power level intake side  
 LwA<sub>out</sub> = Sound power level outlet side · qv = Air flow · p<sub>fs</sub> = Pressure increase