

K3G355-AY40-02

# EC centrifugal module - RadiPac

backward curved, single inlet

with support bracket



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## Nominal data

Type	K3G355-AY40-02	
Motor	M3G112-GA	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min <sup>-1</sup>	2600
Power input	W	1700
Current draw	A	2.6
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	+40

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit  
Subject to alterations

## Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

\* Specific ratio =  $1 + p_{fs} / 100\,000\text{ Pa}$

	Actual	Request 2013	Request 2015
Overall efficiency $\eta_{es}$	66.1	50	54
Efficiency grade N	74.1	58	62
Power input $P_{ed}$	kW	1.72	
Air flow $q_v$	m <sup>3</sup> /h	4325	
Pressure increase $p_{fs}$	Pa	885	
Speed n	min <sup>-1</sup>	2585	

Data established at point of optimum efficiency



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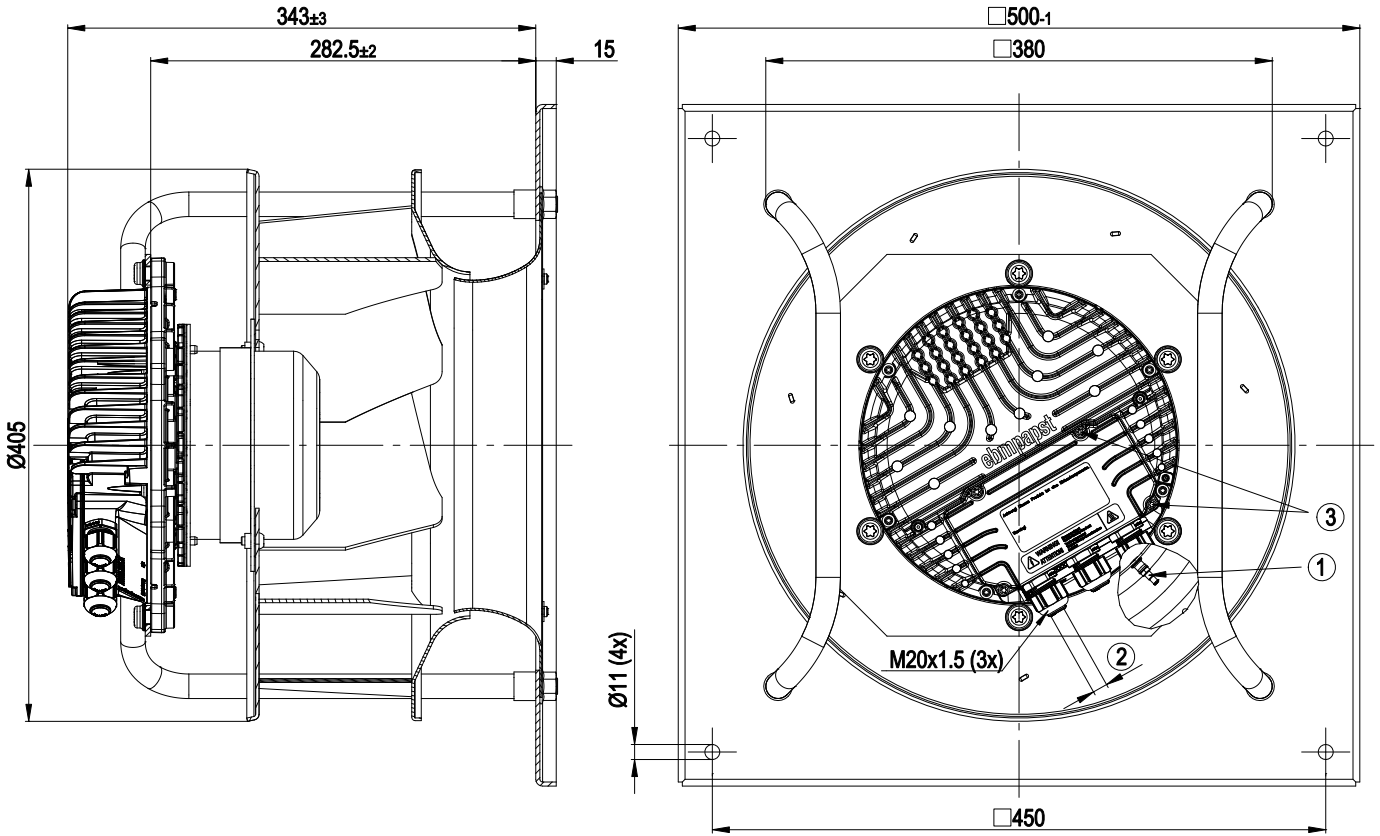
### Technical features

<b>Mass</b>	23 kg
<b>Size</b>	355 mm
<b>Surface of rotor</b>	Coated in black
<b>Material of electronics housing</b>	Die-cast aluminium
<b>Material of impeller</b>	Aluminium sheet
<b>Material of mounting plate</b>	Sheet steel, galvanised
<b>Material of support bracket</b>	Steel, coated in black
<b>Material of inlet nozzle</b>	Sheet steel, galvanised
<b>Number of blades</b>	7
<b>Direction of rotation</b>	Clockwise, seen on rotor
<b>Type of protection</b>	IP 54
<b>Insulation class</b>	"B"
<b>Humidity class</b>	F4-1
<b>Max. permissible ambient motor temp. (transp./ storage)</b>	+80 °C
<b>Min. permissible ambient motor temp. (transp./storage)</b>	-40 °C
<b>Mounting position</b>	Shaft horizontal or rotor on bottom; rotor on top on request
<b>Condensate discharge holes</b>	Rotor-side
<b>Operation mode</b>	S1
<b>Motor bearing</b>	Ball bearing
<b>Technical features</b>	<ul style="list-style-type: none"> <li>- Output 10 VDC, max. 10 mA</li> <li>- Output 20 VDC, max. 50 mA</li> <li>- Output for slave 0-10 V</li> <li>- Input for sensor 0-10 V or 4-20 mA</li> <li>- External 24 V input (programming)</li> <li>- Alarm relay</li> <li>- Integrated PID controller</li> <li>- Motor current limit</li> <li>- PFC, passive</li> <li>- RS485 MODBUS RTU</li> <li>- Soft start</li> <li>- Control input 0-10 VDC / PWM</li> <li>- Control interface with SELV potential safely disconnected from the mains</li> <li>- Over-temperature protected electronics / motor</li> <li>- Line undervoltage / phase failure detection</li> </ul>
<b>EMC interference immunity</b>	Acc. to EN 61000-6-2 (industrial environment)
<b>EMC interference emission</b>	Acc. to EN 61000-6-3 (household environment)
<b>Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)</b>	<= 3.5 mA
<b>Electrical leads</b>	Via terminal box
<b>Motor protection</b>	Thermal overload protector (TOP) wired internally
<b>Protection class</b>	I (if protective earth is connected by customer)

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## Product drawing



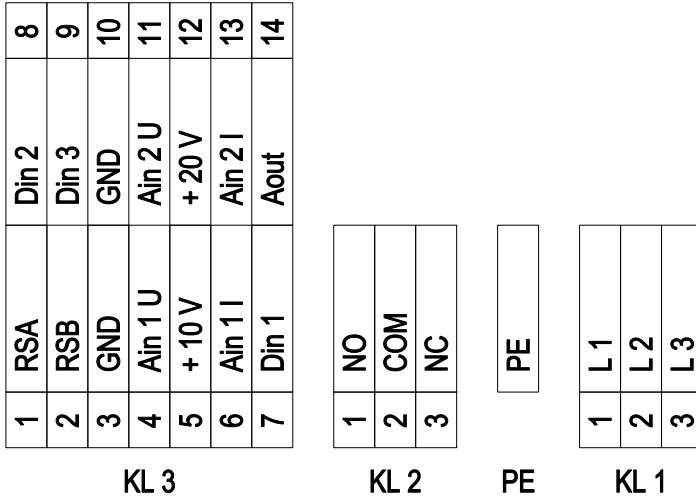
- |   |  |
|---|--|
| 1 | Inlet nozzle with bleeder connection for pressure relief (k-factor: 148) |
| 2 | Cable diameter: min. 4 mm, max. 10 mm, tightening torque: $4 \pm 0.6$ Nm |
| 3 | Tightening torque $3.5 \pm 0.5$ Nm                                       |

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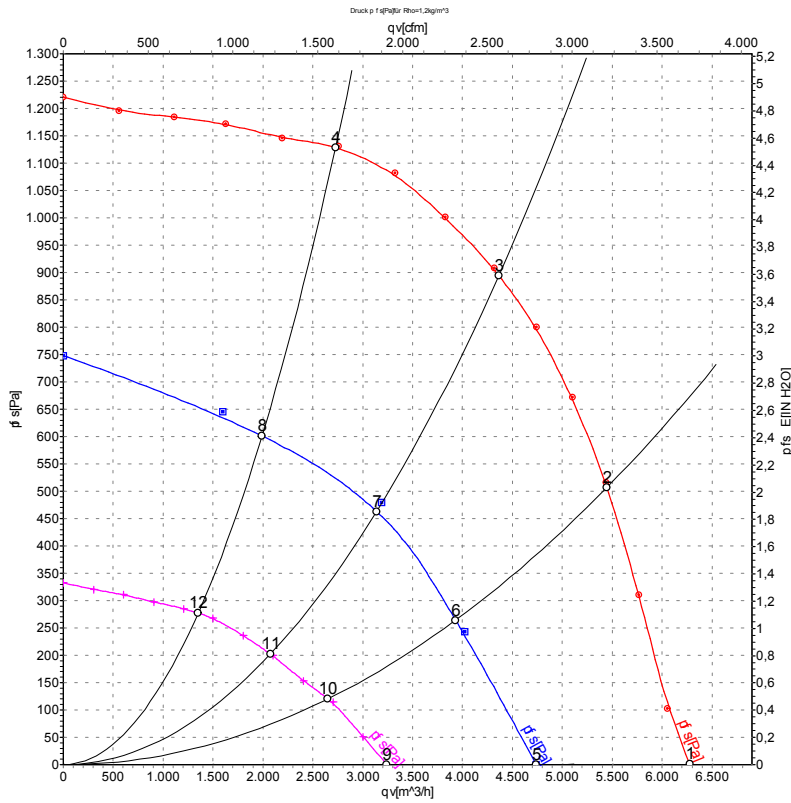
## Connection screen



No.	Pin	Signal	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / 2 A (AC1)
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS485; RSA; MODBUS RTU
KL 3	2	RSB	Bus connection RS485; RSB; MODBUS RTU
KL 3	3 / 10	GND	Signal ground for control interface KL3
KL 3	4	Ain1 U	Analogue input 1 (set value); 0-10 V; Ri= 100 kΩ; parametrisable curves; only usable as alternative to input Ain1 I
KL 3	5	+ 10 V	Fixed voltage output 10 VDC; + 10 V +/-3%; max. 10 mA; short circuit proof; power supply for ext. devices (e.g. potentiometer)
KL 3	6	Ain1 I	Analogue input 1 (set value); 4-20 mA; Ri= 100 Ω; parametrisable curves; only usable as alternative to input Ain1 U
KL 3	7	Din1	Digital input 1: enabling of electronics; enabling: open pin or applied voltage 5 to 50 VDC; disabling: bridge to GND or applied voltage < 1 VDC; reset function: triggers software reset after a level change to <1 V
KL 3	8	Din2	Digital input 2: parameter set switch 1/2; according to EEPROM setting, the valid/used parameter set is selectable per BUS or per digital input DIN2. Parameter set 1: open pin or applied voltage 5 to 50 VDC; parameter set 2: bridge to GND or applied voltage < 1 VDC
KL 3	9	Din3	Digital input 3: Control characteristic of the integrated controller; according to EEPROM setting, the control characteristic of the integrated controller is normally/inversely selectable per BUS or per digital input; normal: open pin or applied voltage 5 to 50 VDC (control deviation = actual sensor value - set value) inverse: bridge to GND or applied voltage < 1 VDC (control deviation = set value - actual sensor value)
KL 3	11	Ain2 U	Analogue input 2; actual sensor value 0-10 V; Ri= 100 kΩ; parametrisable curve; only usable as alternative to input Ain2 I
KL 3	12	+ 20 V	Fixed voltage output 20 VDC; + 20 V +25/-10 %; max. 50 mA; short circuit proof; power supply for ext. devices (e.g. sensors)
KL 3	13	Ain2 I	Analogue input 2; actual sensor value 4-20 mA; Ri= 100 Ω; parametrisable curve; only usable as alternative to input Ain2 U
KL 3	14	Aout	Analogue output 0-10 V; max. 5 mA; output of the actual motor control factor (output voltage of electronics)/ of the actual motor speed; function selectable per bus; parametrisable curve.



## Charts: Air flow 50 Hz



Measurement: LU-106936  
 Measurement: LU-108548  
 Measurement: LU-106951

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

## Measured values

	U	f	n	P <sub>ed</sub>	I	LpA <sub>in</sub>	LwA <sub>in</sub>	LwA <sub>out</sub>	qv	p <sub>fs</sub>
	V	Hz	min <sup>-1</sup>	W	A	dB(A)	dB(A)	dB(A)	m <sup>3</sup> /h	Pa
1	400	50	2600	1140	1.74	85	92	100	6275	0
2	400	50	2600	1510	2.30	76	83	91	5445	515
3	400	50	2600	1700	2.60	73	79	89	4365	900
4	400	50	2600	1594	2.42	76	83	91	2725	1130
5	400	50	1940	436	0.73	78	84	88	4735	0
6	400	50	1910	541	0.88	69	76	81	3930	269
7	400	50	1885	533	0.95	67	73	79	3140	485
8	400	50	1905	558	0.91	69	76	82	1990	604
9	400	50	1330	194	0.40	69	76	81	3240	0
10	400	50	1315	226	0.45	63	70	74	2650	121
11	400	50	1305	239	0.47	59	66	72	2075	203
12	400	50	1305	236	0.46	59	66	72	1350	277

U = Supply voltage · f = Frequency · n = Speed · P<sub>ed</sub> = Power input · I = Current draw · LpA<sub>in</sub> = Sound pressure level inlet side · LwA<sub>in</sub> = Sound power level inlet side · LwA<sub>out</sub> = Sound power level outlet side  
 qv = Air flow · p<sub>fs</sub> = Pressure increase

